# Community Detection via Semidefinite Programming

Federico Ricci-Tersenghi (Sapienza University)

in collaboration with Adel Javanmard and Andrea Montanari

PNAS 113, E2218 (2016) J. Phys.: Conf. Ser. 699, 012015 (2016)

# Communities detection problem

 Detecting communities/partitions/clusters in graphs is a widespread problem in many different disciplines



- We need fast (linear and scalable) algorithms
  - robust (real datasets are very noisy and not random)
  - close to optimal (on random ensemble benchmarks)

# Benchmark for community detection

Hidden partition model or stochastic block model (SBM)

- Generate a partition of n nodes: e.g. q groups of size n/q
- Add independently edges between any pair of nodes according to the following probability

 $\mathbb{P}[(ij) \in E] = \begin{cases} c_{\rm in}/n & \text{same group} \\ c_{\rm out}/n & \text{different groups} \end{cases}$ 

• Assortative model  $c_{in} > c_{out}$ Disassortative model  $c_{in} < c_{out}$ 

The hidden partition model



### The hidden partition model



Colors are not provided !

#### The hidden partition model



The right ordering neither !!

#### The hidden partition model



Given only the adjacency matrix  $A_{ij} = A_{ji} = \mathbb{I}[(ij) \in E]$ 

> Hidden (true) partition ->  $x_0 \in \{+1, -1\}^n$ Estimated partition ->  $\hat{x}(G) \in \{+1, -1\}^n$ Quality of inference via the overlap ->  $Q = \frac{1}{n} |\langle \hat{x}(G), x_0 \rangle|$

#### Assortative SBM with 2 equal-size groups

Relevant parameters and threshold

• Mean degree  $d = \frac{c_{\text{in}} + c_{\text{out}}}{2}$ 

• Signal-to-noise ratio 
$$\lambda = rac{c_{
m in} - c_{
m out}}{2\sqrt{d}}$$

- Bayes optimal threshold  $\lambda_c = 1$ 
  - Impossible detection for  $\,\lambda < \lambda_c\,$
  - BP algorithm with Q > 0 for  $\lambda > \lambda_c$

[Decelle, Krzakala, Moore, Zdeborova, 2011] [Massoulie, 2013] [Mossel, Neeman, Sly, 2013]

# Maximum Likelihood (ML)

 If no information on the generative model is given (apart being assortative and with 2 equal-size groups) a good choice is to <u>maximize the likelihood</u>

maximize 
$$\sum_{i,j} A_{i,j} x_i x_j$$

subject to 
$$x_i \in \{+1, -1\}$$
 and  $\sum_i x_i = 0$ 

• NP-hard problem

### Spectral relaxation

- Relaxes the constraint  $x \in \{+1, -1\}^n$
- Compute largest/smallest eigenvalues of a combination of adjacency (A) and degrees (D) matrices Project the corresponding eigenvector to  $\{+1, -1\}^n$

• Laplacian 
$$L = D - A$$

Eigenvector localization on

- Normalized Laplacian  $D^{-1/2}LD^{-1/2}$  high or low degree nodes
- Bethe Hessian  $H(\lambda) = (\lambda^2 1)\mathbb{I} + D \lambda A$ [Saade, Krzakala, Zdeborova, 2014]
- z-Laplacian  $L_z = zA D$ [Banks, Moore, Newman, Zhang, 2014]

Eigenvector localization on cliques

### Spectral relaxation fails on sparse graphs

$$n = 10^4 \quad \lambda = 1.2$$



 $oldsymbol{v}_1(oldsymbol{A^{ extbf{cen}}})$ 

# Quasi-random graphs (SBM + random cliques)

- Generate a graph according to the SBM
- Choose a subset S of vertices of size  $|S|=\alpha n$
- For each vertex in  ${\cal S}$  connect all its neighbours
- The number of edges increases by  $\sim \alpha d^2 n/2$  i.e. by a fraction  $\sim \alpha d$
- A robust inference method should work also for  $\alpha>0$  at least in the regime  $\,\alpha\ll 1/d\,$





# Quasi-random graphs (SBM + non adversarial cliques)

- Generate a graph according to the SBM
- Choose a subset S of vertices of size  $|S|=\alpha n$
- For each vertex in  ${\cal S}$  connect all its neighbours belonging to the same community
- Non adversarial cliques provide more information

### SBM + cliques

N=10<sup>5</sup> d=4  $\lambda$ =1.1



Q

### SDP: a better relaxation?

• Maximize 
$$\sum_{i,j} A_{i,j} x_i x_j$$
 over  $oldsymbol{x} \in \{+1,-1\}^n$ 

it is equivalent to maximize  $\langle {m A}, {m X} 
angle \equiv \sum_{i,j} A_{ij} X_{ij}$ 

subject to  $oldsymbol{X} \in \mathbb{R}^{n imes n}, \quad oldsymbol{X} \succeq 0$  (i.e. all eigenvalues >= 0)

$$X_{ii}=1$$
 and  $oldsymbol{X}$  being of rank 1

- SDP <u>relaxes the rank</u> and maximizes  $\langle {m A}, {m X} 
  angle$ over the <u>convex</u> space of positive semidefinite matrices
- The maximizer is a matrix of rank  $m \in [1, n]$  to be projected back on a rank 1 matrix...

$$oldsymbol{X}^{ ext{opt}} \longrightarrow oldsymbol{\hat{x}}^{ ext{SDP}} (oldsymbol{\hat{x}}^{ ext{SDP}})^{\mathsf{T}}$$

### SDP-based algorithm

- Maximize  $\langle A, X \rangle$  over rank-m matrices = correlation matrices between m-components variables of unit norm

$$C_{ij} = \underline{x}_i \cdot \underline{x}_j, \text{ with } \underline{x}_i \in \mathbb{R}^m, \|\underline{x}_i\|^2 = \underline{x}_i \cdot \underline{x}_i = 1$$
• Maximize  $\sum_{(ij)\in E} \underline{x}_i \cdot \underline{x}_j$  subject to  $\sum_i \underline{x}_i = \underline{0}$ 

$$\underline{h}_i = \sum_{j\in\partial i} \underline{x}_j - \frac{d}{n} \sum_j \underline{x}_j$$

$$\underline{x}_i \leftarrow \frac{\underline{h}_i}{||\underline{h}_i||}$$

Greedy T=0 dynamics (very fast! no gradient used)

### SDP-based algorithm





- Given the maximizer  $\underline{x}^* = \{\underline{x}_1^*, \dots, \underline{x}_n^*\}$ compute the empirical covariance matrix (m x m)  $\Sigma_{jk} = \frac{1}{n} \sum_{i=1}^n (\underline{x}_i^*)_j (\underline{x}_i^*)_k$
- Project on its principal eigenvector  $\hat{x}_i^{\text{SDP}} = \operatorname{sign}(\underline{x}_i \cdot \underline{v}_1)$

http://web.stanford.edu/~montanar/SDPgraph/

## SDP-based algorithm

- <u>Algorithm complexity</u>  $O(n m t_{conv})$  and <u>quality of inference</u> do depend on m
  - m=1 -> ML, very rough objective function, NP-hard
  - m=n -> SDP, convex objective function no local maxima for  $m>\sqrt{2n}$  [Burer, Monteiro, 2003]
  - m>1, but small -> smooth enough objective function ? local minima are "close enough"  $O(m^{-1/2})$ to global minimum [Montanari, 2016]
- Running times grows very mildly with m and n e.g. if stopping rule is max variation < 10^{-3} ->  $t_{
  m conv} \propto n^{0.22}$

#### Small m values are fine!

$$n = 4 \cdot 10^4 \quad d = 3 \quad \lambda = 1.1 \quad \alpha = 0.0$$



#### The algorithm is very fast!

$$n = 10^5$$
  $d = 3$ 



Q<sup>SDP</sup>

#### The algorithm is very robust!

$$n = 4 \cdot 10^4 \quad d = 3 \quad \lambda = 1.1$$



The algorithm is very robust!  $N=10^5 d=4 \lambda=1.1$ 



t

# A real-world network (political blogs)

1222 nodes, 16714 edges

|                              | overlap  | cut size |
|------------------------------|----------|----------|
| Bethe Hessian<br>z-Laplacian | 0.865794 | 1271     |
| Adjacency                    | 0.86743  | 1268     |
| X-Laplacian                  | 0.918167 | 1250     |
| Low rank SDP                 | 0.903437 | 1221     |
| "ground truth"               | 1.0      | 1575     |



#### A quantitative comparison





- We estimate  $\lambda_c^{\rm SDP}$  by solving the statistical physics of models with m-component spin variables, in  $m\to\infty$  limit
  - Running the SDP-based algorithm for very large m values (= solve the exact cavity equations)
  - Solving analytically via an approximate ansatz

### SDP quasi-optimality



### Computing the threshold

- Crossing of the Binder cumulants to locate exactly  $\lambda_c^{ ext{SDP}}$ 



### Computing the threshold

- Crossing of the Binder cumulants to locate exactly  $\lambda_c^{ ext{SDP}}$ 



### Statistical physics analytical approach

• <u>Unified framework</u>: statistical physics models with m-component variables:  $\underline{x}_i \in \mathbb{R}^m$ ,  $||\underline{x}_i|| = 1$ 

$$P(\underline{x}) = \frac{1}{Z} \exp\left[\beta \sum_{(ij)\in E} \underline{x}_i \cdot \underline{x}_j\right]$$

- Bayes: m = 1,  $\tanh(\beta) = \lambda/\sqrt{d}$
- ML:  $m=1, \quad \beta \to \infty$
- SDP:  $m \to \infty, \quad \beta \to \infty$

### Statistical physics analytical approach

• Ansatz for the marginals in m-component <u>dense</u> models

$$P_i(\underline{x}_i) = \frac{1}{Z_i} \exp\left[2m\beta(\underline{\xi}_i^\mathsf{T}\underline{x}_i + \underline{x}_i^\mathsf{T}\boldsymbol{C}_i\underline{x}_i)\right]$$

$$\underline{x}_i \in \mathbb{F}^m , ||\underline{x}_i|| = 1 \qquad \underline{\xi}_i \sim \mathcal{N}(\underline{\mu}, Q) \qquad C_i = C$$

• Self consistency equations in the dense case

$$\underline{\mu} = \lambda \mathbb{E}[\langle \underline{x} \rangle]$$
$$Q = \mathbb{E}[\langle \underline{x} \rangle \langle \underline{x}^{\mathsf{T}} \rangle]$$
$$C = \beta m \mathbb{E}[\langle \underline{x} \underline{x}^{\mathsf{T}} \rangle - \langle \underline{x} \rangle \langle \underline{x}^{\mathsf{T}} \rangle]$$

#### Analytical solution: dense real case

$$MSE_{n}(\hat{\boldsymbol{x}}) \equiv \frac{1}{n} \mathbb{E} \left\{ \min_{s \in \{+1,-1\}} \left\| \hat{\boldsymbol{x}}(\boldsymbol{Y}) - s \, \boldsymbol{x}_{0} \right\|_{2}^{2} \right\}$$



# Phase diagrams in the sparse case (SBM d=4) <u>Ising</u> (m=1)



#### Phase diagrams in the sparse case (SBM d=4)

XY model (m=2)



 In the recovery phase we assume the O(m) symmetry to break along the first component, while preserving O(m-1)

$$\underline{x}_i = (s_i, \boldsymbol{\tau}_i), \, s_i \in \mathbb{R}, \, \boldsymbol{\tau}_i \in \mathbb{R}^{m-1}$$

• We write the marginal for  $\underline{x}_i$  as

 $\exp\left\{2\beta\sqrt{mc_i}\langle \boldsymbol{z}_i,\boldsymbol{\tau}_i\rangle+2\beta mh_i\,s_i-\beta mr_is_i^2+O_m(1)\right\}\delta\left(s_i^2+\|\boldsymbol{\tau}_i\|_2^2-1\right)$ 

with  $oldsymbol{z}_i \sim \mathsf{N}(0, \mathrm{I}_{m-1})$ 

- Approximate because the  $z_i$  are correlated
- It should be valid in the limits  $d \to 1$  and  $~d \to \infty$

$$\exp\left\{2\beta\sqrt{m}\mathbf{c}_{i}\left\langle\boldsymbol{z}_{i},\boldsymbol{\tau}_{i}\right\rangle+2\beta mh_{i}s_{i}-\beta mr_{i}s_{i}^{2}+O_{m}(1)\right\}\delta\left(s_{i}^{2}+\|\boldsymbol{\tau}_{i}\|_{2}^{2}-1\right)$$

Cavity method -> self consistency equation for marginals



- Solve by population dynamics
- At the fixed point  $Q^{\text{SDP}} = \mathbb{E}[\operatorname{sign}(h^*)]$



- Linearize the cavity equations to locate the threshold
- To linear order in  $h \implies r_i = 0$





## Analytical solution: sparse case (SBM)

• SDP at most 2% sub-optimal!



- Red points: numerical solution of the replica/cavity equations (crossing of Binder cumulants)
- Black line: approximated analytical solution

#### Some conclusions...

- SDP relaxations are very effective:
  - robust and quasi-optimal
  - may outperform spectral relaxations
- Better than SDP are SDP-inspired algorithms (small m) http://web.stanford.edu/~montanar/SDPgraph/
- It is worth studying the statistical physics of models with m-component variables:
  - unifying framework to study and solve several estimators in statistical inference
  - different physics, better algorithms